This document provides instruction for prosthetists in the fitting and servicing of the i-limb access and should be read in full prior to fitting. It is highly recommended that the use of this manual is made in conjunction with instruction from a clinician experienced in upper limb and myo-electric prostheses.

⚠️ This symbol signifies important information and is used throughout the manual.

Refer to www.touchbionics.com/downloads/document-library to ensure you have the latest copy of this document.
Table of Contents

1. i-limb access  
   1.1 Product Description  
   1.2 Intended Use  
   1.3 Prosthesis Overview  

2. Socket  
   2.1 Control Sites  
   2.2 Socket Fabrication  
   2.3 Charge Port Placement Assembly  
   2.4 Battery Options  
   2.5 Battery Configuration  
   2.6 Battery Installation  
   2.7 Battery Charging  

3. Wrist  
   3.1 Wrist Connection Options  
   3.2 Quick Wrist Disconnect (QWD)  
   3.3 Wrist Disarticulation  
   3.4 Multi-flex Wrist  
   3.5 Flex Wrist  

4. Adjustments  
   4.1 Digit Configuration  
   4.2 Digit Installation  
   4.3 Thumb Installation  

5. Covers  
   5.1 Cover Options  

6. Grip Review  
   6.1 Features Catalogue  

7. Support Information  
   7.1 Storage and Maintenance  
   7.2 Troubleshooting  
   7.3 General Safety, Warnings and Precautions  

8. User Information  
   8.1 User Details  

9. Appendix  
   9.1 Technical Information  
   9.2 i-limb access Information  
   9.3 Component Compatibility  
   9.3.1 EMC and Electrical Information  
   9.4 Warranty
1.0 i-limb access

1.1 Product Description

The i-limb access is an externally powered, multi-articulating prosthetic hand which offers a range of features beyond the functions of the traditional prosthetic hand.

Individually motorized digits, stall detection and the unique biosim software used to control the i-limb access result in one of the most versatile prosthetic hands currently available to the global market.

Users can choose from a wide selection of automated grips and gestures to help complete daily tasks.

The i-limb access offers compliant grip through individually powered digits with stall out ability. A manually rotating thumb, a slip preventing feature (anti-drop), safety feature (auto-grasp) and the wide range of automated grip patterns lead to broad functionality.

1.2 Intended Use

The i-limb access is intended to be used by patients with upper limb loss or deficiency.

1.3 Prosthesis Overview

The i-limb access is available in either black or neutral colors, as well as small or medium sizes (see technical specifications in section 9.1 for actual measurements). The hand serial number is positioned proximal to the base of the thumb on the connection plate. The serial number should start with the letter “A” and be followed by four numbers (also highlighted in biosim, see section 6).
2.0 Socket

2.1 Control Sites

One option for control of the i-limb access is electrodes.

There are two electrode options available for use with the i-limb access, compact electrodes (fig. 1) or remote electrodes (fig. 2). For information regarding the fitting of the Touch Bionics Electrode, review the manual provided with the electrode.

Electrode Site Selection

The use of virtu-limb, the Touch Bionics’ myotesting system, is recommended to determine the optimal placement of electrodes (fig. 3).

⚠️ Do not rely on previous myoelectrical testing.

Consult Touch Bionics training materials for information on myotesting or download information on myotesting within the software or mobile apps manuals at www.touchbionics.com/downloads/document-library.

⚠️ Use anatomical sites where the electrode will maintain constant, even contact with the skin. Avoid placing electrodes near socket interface trim lines, bony areas, skin grafts or fatty tissue.
2.2 Socket Fabrication

While fabricating the socket for the i-limb access, special considerations will need to be given to:

1. Battery placement, size and configuration
2. Electrode position or other control method
3. Charge port placement
4. Socket length and the overall length of the prosthesis in comparison to the opposite side.

Clinicians should have prior experience with building externally powered prosthetic sockets before fitting the i-limb access.

Touch Bionics’ batteries, charger port and switch block components should always be used with the i-limb access.

**Prosthetist must ensure that the plastic screw provided is utilized and properly tightened on the coaxial plug (fig.4) where the battery and electrodes connect, to prevent loose connections.**

**We recommend that a rubber grommet or plastic cap is placed over any socket holes to protect the integrity of the electrode.**

**During socket maintenance, ensure a check of the battery connector/co-axial plug interface is carried out.**

**Socket Material**

The use of Carbon fiber is not recommended due to electrical conductivity, if it is required to improve strength then the carbon fiber lamination must be grounded, if used directly adjacent to electrodes (see Page 6). Please contact Touch Bionics to order modified electrodes.

During socket fabrication, appropriate measures must be taken to prevent sweat entering into the battery connector within the lamination ring, which may result in a short circuit and compromise use of the device. Conventional sweat prevention methods include the use of drain holes and suction sealing electrodes. Alternatively, silicone may be used to seal the interface area between the battery connector and co-axial plug into the prosthetic socket.

**Coupling Piece Assembly for QWD Wrist**

Insert the castellation ring (coupling piece) into the lamination ring and turn until seated. Insert retaining ring around the outside edge of the coupling piece and use QWD release tool to seat the retaining ring. The QWD release tool is available to order from Touch Bionics.
2.3 Charge Port Placement Assembly

It is important to provide sufficient space for the charge port between the inner and outer sockets. The charge port should be positioned so that it is unaffected by forces running through the socket to prevent damage.

Create a drill hole of 8.0mm through the inner surface of the prosthetic frame. Ensure a flat surface has been created to accommodate the charge port mounting frame (if installing a switch block as an alternative to the charger port, create a drill hole to cater for the panel mount).

Smooth the edges of the drill hole and insert the threaded charge port. A minimum thread height of 3.2mm above the socket surface is required for full engagement of washers and locking nut.

Position the M8 Lock Washer and the M8 Flat Washer before hand tightening the the locking nut.

Use a 3/8" wrench to tighten the locking nut. Do not overtighten.

- Do not use pliers on the charge port.
- Position the M8 Lock Washer and M8 Flat Washer in place over the threaded shaft of the charger port. Engage the M8 locking nut with the threaded shaft and tighten firmly by hand.
- The use of both the Lock Washer and Flat Washer is vital to ensure the charge port is not damaged by over tightening.
- Do not overtighten!
2.4 Battery Options

The i-limb access comes with a 1,300mAh battery. This battery has been specifically designed to meet the power requirements of the hand. The corresponding DC socket will also be required.

<table>
<thead>
<tr>
<th>Battery Dimensions</th>
<th>Length</th>
<th>Width</th>
<th>Height</th>
</tr>
</thead>
<tbody>
<tr>
<td>Capacity</td>
<td>1,300 mAh</td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td>70mm (2.76&quot;)</td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td>35mm (1.39&quot;)</td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td>6mm (0.24&quot;)</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Dummy Battery Dimensions</th>
<th>Length</th>
<th>Width</th>
<th>Height</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>69mm (2.77&quot;)</td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td>35mm (1.39&quot;)</td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td>10mm (0.39&quot;) Single cell</td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td>16mm (0.63&quot;) Dual cell</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

| Application | Moderate Use |

2.5 Battery Configuration

The images opposite show the 1,300mAh battery options with battery dummy. The battery with DC connector and battery with switch block connector are shown.

Only Touch Bionics batteries are approved for use with the i-limb access. Use of alternative batteries will invalidate the warranty and compromise general safety of the device.
2.6 Battery Installation

The battery is designed to be mounted inside the socket interface. Ensure there is adequate space between the residual limb and the wrist (or elbow) to accommodate the battery, charger port and any other componentry. Use the battery dummy to fabricate a relief for the battery in the socket interface.

When planning battery location and dummy placement for fabrication, keep in mind a maximum distance of 135mm is possible between cells due to wire length.

Easier access to the on/off switch may be possible by installing a switch block; this allows the on/off switch to be positioned in a more proximal position on the forearm. The use of a switch block also provides an additional accessory switch for temporarily disabling an electric wrist rotator or other electrical device, when needed.

Battery Placement

Use Velcro™ to position the batteries on the pre-prepared flat surfaces to prevent distortion.
Battery Placement for a Long Residual Limb

Consideration of battery placement is particularly important in longer sockets. The shape of the inner socket must also be considered.

If the residual limb is long, wrist disarticulation or bulbous, the position of the battery dummies and charge port are best placed midway up the arm along the inner socket ensuring they will not impact the ability to don/doff the prosthesis and that the position will not result in pressure from the residual limb that could distort the battery.

Placement of batteries should allow for removal of the inner socket.

If the socket has a bulbous distal end, do not position batteries or charger port around the narrow region of the prosthesis.

A minimum of 2mm of free space should be provided surrounding the charger port or switch block.

A flat surface is needed to secure the charger port to the socket interface frame. This may require additional shaping of the frame section above the dummy battery. Use the Velcro® strip supplied to attach the battery to the inside of the socket interface.

If the area between the residual limb and the lamination ring is insufficient to house the battery, you will need to position the battery between the socket interface and the frame. This will be necessary when:

- the residual limb is longer than 60% of the humeral or forearm section of the prosthesis
- the residual limb is a wrist or elbow disarticulation
- the battery is too large for the space available in the socket interface frame

Cutting or modifying the battery wires in any way will invalidate the warranty.

Do not bend or shape the battery in any way.

Ensure the battery is not subject to continued pressure once fitted.
2.7 Battery Charging

Please review the below instructions for proper battery charging.

**Important:** Only use supplied Touch Bionics charger to charge battery. Depending on your location, you will receive one of the below chargers (fig. 6 or fig. 7).

The patient will need to remove the socket from their arm and turn the i-limb device off. The on/off switch is pictured in fig 5. i-limb device is off when switch is in left position.

Insert the charger (fig. 6 or fig. 7) into the power outlet. The charger will need to be inserted into the power outlet prior to connecting to the charge port. To charge, insert the charger lead connector into the charge port. A “click” should be heard on connection. If the green light is on when you first plug in the device, ensure the hand is off.

Charging time is approximately:

1,300 mAh battery - 90 minutes

The light display for fig. 6 is:

- **Solid Red** – charging
- **Solid Green** – fully charged or idle
- **Continuous flashing red** – fault condition
- **Rapid flashing amber** – Threshold state between charging and fully charged (should only last for 1-2 seconds)
- **Continuous flashing red or green** – Connection Error.
  Remove charger lead connector from the charge port.
  Ensure charger is plugged in and switched on at the mains.
  Re-insert the charger lead connector into the charge port.

The light display for fig. 7 is:

- **Solid Amber** – on standby
- **Slow flashing amber** – pre-charge mode
- **Rapid flashing amber** – Error
- **Slow flashing green** – maintenance charge
- **Rapid flashing green** – rapid charge
- **Solid green** – fully charged

To remove the charger lead connector from the i-limb access, grip the connector and pull directly away from the port. Consult Warnings and Precautions for additional information.

If the patient intends to travel outside of their home country, they will need to ensure they have a Touch Bionics charger that will work in the country to which they are traveling. Additional chargers are available from Touch Bionics.

As an alternative to your patients charging directly from domestic power, a car charger (fig. 8) is provided with the i-limb access.

- **To ensure the i-limb access is continually functional, charge at the end of each day.**
- **Do not pull cable to remove the lead.**
- **Replace the battery annually for optimal performance.**
- **Switch the hand OFF to preserve battery power when not in use.**
3.0 Wrist

3.1 Wrist Connection Options

i-limb access is available with the following wrist options:

1. Quick Wrist Disconnect (QWD)
2. Wrist Disarticulation

The following flexible wrist options are available for the i-limb access:

1. Multi-flex Wrist
2. Flex Wrist

3.2 Quick Wrist Disconnect (QWD)

The QWD is supplied by Touch Bionics.

Connecting the i-limb access using the QWD

1. Ensure the i-limb access is switched off.
2. Align the QWD connection of the i-limb access with the connection in the forearm socket.
3. Engage the coupling.

4. Test the connection is fully engaged with a slight rotation.

Disconnecting the i-limb access using the QWD

1. Ensure the i-limb access is switched off.
2. Support the i-limb access in the palm of the hand.
3.3 Wrist Disarticulation

The wrist disarticulation frame or “attachment plate” is fabricated directly into the socket frame and then attached to the i-limb access by the following steps:

1. Disconnect the palm fairing from the i-limb access chassis by unscrewing the screw in the palmar surface using a T10 screwdriver (available for order).

2. Rotate the i-limb access through 360° in either direction until a click is heard.

3. The i-limb access will now disengage from the socket. Support the hand and withdraw away from the socket.
2. Remove the wrist disarticulation basket and feed the power cable through the attachment plate.

3. Align the slots and slide the Wrist Disarticulation basket onto the Lamination Plate at base of the i-limb access ensuring it is firmly engaged.

4. Secure the Wrist Disarticulation basket to the Lamination Plate at the base of the i-limb access using the T10 screw and T10 Screwdriver (ordered separately).

5. Replace the Palm Fairing onto the chassis by hand tightening the screw in the palmar surface using the T10 Screwdriver supplied. Ensure that the palm fairing does not pinch the wiring.
Fabrication of the wrist disarticulation into the socket must allow for disengagement of the hand from the lamination plate at the base of the i-limb access. Otherwise, complete fabrication of the wrist disarticulation into the socket in the usual manner.

To disconnect the Wrist Disarticulation from the i-limb access complete the above steps in reverse:

1. Disconnect the Palm Fairing from the Chassis. Be careful to not damage wring when removing the Palm Fairing.
2. Loosen the wrist disarticulation lamination plate screw from the wrist disarticulation plate.
3. Slide the wrist disarticulation basket off the lamination plate at base of the i-limb access.
4. Separate the i-limb access from the wrist disarticulation, drawing the power cable through the wrist disarticulation.

For guidance on fabrication consult section 2.2 Socket Fabrication.

3.4 Multi-flex Wrist

The Multi-flex Wrist is connected directly to a QWD and can be used in either passive or locked mode. Passive mode allows spring-loaded flexion, extension and lateral deviation. Locked positions options are 30° dorsiflexion, 0° neutral and 30° palmar flexion. The control switch for locking is located on the medial / lateral portion of the wrist and is covered by the flexible wrist sleeve. (See i-limb access multi-flex data sheet for more information on the Touch Bionics website: www.touchbionics.com/downloads/document-library/).

Note: when unlocking, you must disengage the spring by putting pressure against the hand in the direction the hand was locked.
3.5 Flex Wrist

The Flex Wrist is connected directly to a QWD and offers three wrist positions, 30° dorsiflexion, 0° neutral and 30° palmar flexion. The control switch is positioned on the palmar surface of the wrist and is manually operated. (See i-limb access flex data sheet for more information on the Touch Bionics website: www.touchbionics.com/downloads/document-library/).
4.0 Adjustments

4.1 Digit Configuration

Individual digits for the i-limb access are manufactured as sizes 2, 3, 5 and 6. Sizes 2 and 3 contain a small motor, while sizes 5 and 6 contain a larger motor. The standard digit configuration of the small and medium sized i-limb access is outlined in Table 1.

<table>
<thead>
<tr>
<th>Digit</th>
<th>Small</th>
<th>Medium</th>
</tr>
</thead>
<tbody>
<tr>
<td>Thumb</td>
<td>5</td>
<td>6</td>
</tr>
<tr>
<td>Index</td>
<td>5</td>
<td>6</td>
</tr>
<tr>
<td>Middle</td>
<td>5</td>
<td>6</td>
</tr>
<tr>
<td>Ring</td>
<td>3</td>
<td>5</td>
</tr>
<tr>
<td>Little</td>
<td>2</td>
<td>2</td>
</tr>
</tbody>
</table>

4.2 Digit Installation

The i-limb access is only compatible with Touch Bionics digits. To install a digit, ensure that the correct digit size is selected. Remove the digit by the following steps:

1. Ensure the i-limb access is switched off.

2. Support the i-limb access in the palm of the hand with the digits in the fully open position. Insert the T10 Screwdriver in the screw of the knuckle block (available for order).

3. Loosen the knuckle block screw while supporting the digit, and remove the digit.

4. Select the appropriate sized replacement digit and follow the steps in reverse order to replace.
4.3 Thumb Installation

The i-limb access is only compatible with Touch Bionics i-limb access digits. To exchange a thumb ensure the correct size has been selected.

Instruments required: T10 Screwdriver (available for order)

1. Support the i-limb access in the palm of the hand.

2. Fully rotate the thumb to its lateral prehension position.
3) Disconnect the palm fairing using the T10 screwdriver to loosen the palmar T10 screw.

4) Gently move the palm fairing to the ulnar side to allow access to the exposed T10 screw at the base of the thumb.

5) Using the T10 Screwdriver access the screw from the medial to lateral direction to loosen.

6) The thumb is now easily removed from the knuckle block.
7. Position the replacement thumb in the knuckle block and follow the above steps in the reverse order to reconstruct the hand. When replacing the palm fairing, ensure wires are not pinched between the palm fairing and the chassis.

It is recommended that you discard the used screws as the anti-vibration pad on the screw shaft will be deformed during use. Digit screws should be replaced using the new screws provided.

- ! Do not over tighten screws.

- ! Do not re-use screws.

- ! If there is resistance while tightening the screw, check for cross threading by removing and re-inserting the screw.

- ! Touch Bionics recommends T10 Screwdriver for use with all T10 screws in the i-limb access.
5.0 Covers

5.1 Cover Options

Coverings are an important part of the appearance and durability of upper limb prostheses. The Touch Bionsics i-limb products are the first prosthetic hands and fingers to imitate the individual digit articulation of the human hand, and we provide flexible coverings which enable that articulation. Our covering solutions include:

i-limb skin active:
For users who prefer the robotic nature of the uncovered i-limb prosthesis, i-limb skin active is a thin layer of semi transparent or black material that has been designed to conform to every contour of the hand.

i-limb skin active TS:
In addition to all the benefits of the i-limb skin active, the i-limb skin active TS allows users to use touchscreen devices such as smartphones or tablets with compatible i-limb prostheses.

i-limb skin natural:
Providing the user a lifelike silicone covering, i-limb skin natural is available with 18 different skin shades. Benefits include:
- Don or doff in under a minute without the assistance of a clinician
- Improved design optimizes hand power and precision pinch mode

i-limb skin match:
For the most realistic covering option possible, this is a fully customized silicone covering that exactly matches the user’s skin tone and features.

Please consult the Coverings Care Guide for donning and doffing instructions as well as tips on wear and care. Coverings Care Guide is available online at www.touchbionics.com/downloads/document-library.

Please contact your clinician for ordering information.

The cover of the i-limb access is very important. The i-limb access should not be used without an approved cover that is well maintained.
6.0 Grip Review

The i-limb access has 12 different Quick Grip options available. These Quick Grips can be accessed through biosim-pro and the biosim app. The following features catalogue will review the various available Quick Grips and provide a functional description of each.

For more information about biosim-pro or the biosim app, please consult their respective manuals at www.touchbionics.com/downloads/document-library.

6.1 Features Catalogue

Precision Pinch Grip Options

Standard Precision Pinch Opened
Middle, ring and little finger remain fully opened and switch off. Index finger and thumb provide grip.

Standard Precision Pinch Closed
Middle, ring and little finger automatically close and switch off. Index finger and thumb provide grip.

Thumb Precision Pinch Opened
Middle, ring and little finger remain fully opened and switch off. Thumb automatically moves to a partially closed position. Index finger will move to provide grip against a fixed thumb.

Thumb Precision Pinch Closed
Middle, ring and little finger automatically close and switch off. Thumb automatically moves to a partially closed position. Index finger will move to provide grip against a fixed thumb.

Tripod Grip Options

Standard 3 Jaw Chuck (Tripod) Opened
Ring and little finger remain fully opened and switch off. Thumb, index and middle fingers move to provide grip.

Standard 3 Jaw Chuck (Tripod) Closed
Ring and little finger move to terminal close. Thumb, index and middle fingers move to provide grip.

Thumb 3 Jaw Chuck (Tripod) Opened
Ring and little finger remain fully opened and switch off. Thumb automatically moves to a partially closed position. Index and middle fingers move to provide grip against a fixed thumb.

Thumb 3 Jaw Chuck (Tripod) Closed
Ring and little finger move to terminal close. Thumb automatically moves to a partially closed position. Index and middle fingers move to provide grip against a fixed thumb.
Additional Grip and Gesture Options

Thumb Park Continuous
All four fingers remain open and switch off, only the thumb will move.

Lateral Grip
All four fingers fully close and switch off. Only thumb will move.

Thumb Park Quick
All four fingers remain open and switch off, for 1.5 seconds the thumb will close and then automatically return to an open position.

Index Point
Thumb, little, ring and middle fingers close and switch off. Only the index finger will move.
7.0 Support Information

7.1 Storage and Maintenance

Always turn off the hand when not in use.

Aim to charge the battery each day after use.

Replace the battery every 12 months.

Ensure i-limb access is serviced every 12 months.
## 7.2 Troubleshooting

<table>
<thead>
<tr>
<th>Problem</th>
<th>Action</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>Hand does not operate</strong></td>
<td>Ensure the hand is switched on</td>
</tr>
<tr>
<td></td>
<td>Ensure the battery is connected</td>
</tr>
<tr>
<td></td>
<td>Ensure the battery is charged</td>
</tr>
<tr>
<td></td>
<td>Ensure the hand is engaged at the wrist</td>
</tr>
<tr>
<td></td>
<td>Check the electrodes have good contact</td>
</tr>
<tr>
<td></td>
<td>Check that the electrode cable is installed correctly (grey side out)</td>
</tr>
<tr>
<td><strong>One digit does not operate</strong></td>
<td>Check if the digit operates correctly using the Hand Health Check in biosim</td>
</tr>
<tr>
<td></td>
<td>Exchange digit with an alternative working digit from same or different i-limb access and re-check. If replaced digit works, contact Touch Bionics.</td>
</tr>
<tr>
<td><strong>Hand stops halfway during an action</strong></td>
<td>Electrode settings may need to be adjusted</td>
</tr>
<tr>
<td></td>
<td>Check the electrode cable is not damaged</td>
</tr>
<tr>
<td></td>
<td>Check the battery cable is not damaged</td>
</tr>
<tr>
<td></td>
<td>Check that the i-limb access is connected correctly to the wrist</td>
</tr>
<tr>
<td></td>
<td>Contact Touch Bionics</td>
</tr>
<tr>
<td><strong>User complains that the hand is difficult to operate</strong></td>
<td>Electrode settings may be too low</td>
</tr>
<tr>
<td></td>
<td>Ensure the battery has good charge</td>
</tr>
<tr>
<td></td>
<td>Ensure the electrodes maintain good contact</td>
</tr>
<tr>
<td></td>
<td>Check electrode placement and wiring.</td>
</tr>
<tr>
<td></td>
<td>Contact Touch Bionics</td>
</tr>
<tr>
<td><strong>Battery charge does not last a full day</strong></td>
<td>Fully charge the battery overnight. Check the battery connection.</td>
</tr>
<tr>
<td></td>
<td>Ensure electrodes are not set above 5.5</td>
</tr>
<tr>
<td></td>
<td>Check user is not holding a sustained signal to the hand. Refer to section 6.3.2 for proper control strategy</td>
</tr>
<tr>
<td></td>
<td>Replace the battery</td>
</tr>
<tr>
<td></td>
<td>Contact Touch Bionics</td>
</tr>
<tr>
<td><strong>The hand will open but not close</strong></td>
<td>Check that the electrode cables are attached are making good contact</td>
</tr>
<tr>
<td></td>
<td>Check the hand is engaged at the wrist</td>
</tr>
<tr>
<td></td>
<td>Check electrode operation by swapping the electrode connections at the lamination ring</td>
</tr>
<tr>
<td></td>
<td>Contact Touch Bionics</td>
</tr>
<tr>
<td><strong>Hand opens when a close signal is provided</strong></td>
<td>Check box in biosim or switch the electrode connections on the lamination ring</td>
</tr>
<tr>
<td><strong>Battery is not working</strong></td>
<td>Check the battery is connected</td>
</tr>
<tr>
<td></td>
<td>Check the battery is charged</td>
</tr>
<tr>
<td></td>
<td>Check the wiring for signs of damage</td>
</tr>
<tr>
<td></td>
<td>Ensure that the charging port is not compressed by the inner and outer socket interface</td>
</tr>
<tr>
<td></td>
<td>Ensure the male connector from the charger is fully inserted into the charger port</td>
</tr>
<tr>
<td></td>
<td>Ensure that the connection between charger lead and port is good</td>
</tr>
</tbody>
</table>

For additional FAQ's please visit our website at: www.touchbionics.com
7.3 General Safety, Warnings and Precautions

i-limb access

Do not use without an approved cover.
Do not use under water.
Do not use to operate heavy / industrial machinery.
Do not use with machinery with moving parts that may cause personal injury or damage.
Users must comply with local regulations on the operation of automobiles, aircraft, sailing vessels of any kind and any other motorized vehicle or device.
Do not use for extreme activities that may cause injury to a natural hand.
Do not expose to excessive moisture, liquid, dust, vibration or shock.
Do not expose to high temperatures.
Do not expose to flames.
Do not use or expose to explosive atmospheres.
Do not disassemble componentry or modify in any way.
Maintenance, repairs and upgrades may only be performed by qualified Touch Bionics technicians and technical partners.
Do not use with a damaged cover.
Damaged covers must be replaced or repaired by a qualified Touch Bionics technician or technical partner.
Only approved Touch Bionics accessories and tooling may be used with the i-limb access.
If utilizing a muti-flex wrist, the i-limb device should be locked if carrying an object.
Do not use an i-limb device to operate your mobile device whilst it is connected to a mains outlet, as this can affect EMG signal.
Failure to comply with the above guidelines will invalidate the warranty.

Batteries

Do not bend or exert excessive pressure on the battery.
Do not pierce the battery.
Do not disassemble.
Do not expose to high temperatures.
Do not incinerate batteries.
Do not alter battery terminal wires.
Do not short circuit the battery.
Do not store batteries inside a vehicle.
Dispose of batteries in accordance with US, European or local regulations.
Only use the appropriate Touch Bionics charger to charge Touch Bionics batteries.
If the battery has visibly ballooned or swelled:
- discontinue the charging process immediately
- disconnect the battery
- remove to a safe area
- leave and observe for 15 minutes
- replace with new battery
- do not re-use
- dispose of any leaking batteries in an appropriate manner
Failure to comply with the above guidelines will invalidate the warranty.

If you experience technical problems with the i-limb access contact Touch Bionics as follows:

North American Customers
(Canada, Mexico & US)
Tel:+1 855 MYiLIMB (694 5462)
UK & Non-North American Customers
Tel: +44 1506 438 556
Driving of Motor Vehicles

The i-limb device has the functional capability to assist a patient with driving a motor vehicle however due to factors including the differences in world-wide driving regulations and the variations in the level of ability between patients Touch Bionics is unable to provide definitive advice in respect to a patient with an i-limb device driving a motor vehicle.

Touch Bionics is aware that patients have used the i-limb to drive a motor vehicle and our recommendations prior to a patient doing so would include the following:

- contacting the driving authority in your home location to obtain and understand the local regulations;
- working with the appropriate authorities to have your car modified to meet the local regulations for your respective disabilities as required;
- re-taking any mandatory driving test using your i-limb device to demonstrate your ability to operate a motor vehicle safely if required by local regulations;
- contacting your insurance provider and advise them that you will be using the i-limb device to drive a motor vehicle;
- ensuring that the device has a fully charged battery. Please note that the i-limb device will emit a low battery signal which will alert you if the battery requires to be charged;
- switching off the i-limb device. This is due to the possibility of involuntary muscle signals being generated; and
- moving the thumb into the lateral position to allow the i-limb to be removed from the steering wheel without opening the hand.

It is entirely the patient’s responsibility to seek confirmation that they are physically and legally able to drive using the device and to the fullest extent permitted by law Touch Bionics shall under no circumstances whatsoever be liable to the patient or any other party as a result of or in connection with a patient with an i-limb device driving a motor vehicle.
8.0 User Information

8.1 User Details

Provision of the following information will enable easy identification of your prosthesis, should it be returned to customer service. Please forward to Touch Bionics as per the contact information on the back page of this manual.

User Name: 
Fitting Date: 
Hand Purchase Date: 
Hand Serial Number: 
Prosthetist Name & Contact Information: 
Therapist Name & Contact Information: 

It is recommended that the above information is also included in the patient notes.
9.0 Appendix

9.1 Technical Information

<table>
<thead>
<tr>
<th>i-limb access</th>
<th></th>
</tr>
</thead>
<tbody>
<tr>
<td>Voltage</td>
<td>7.4 V (nominal)</td>
</tr>
<tr>
<td>Max. Current</td>
<td>5 A</td>
</tr>
<tr>
<td>Battery Capacity</td>
<td>Rechargeable lithium polymer; 7.4 V (nominal); 1,300 mAh capacity</td>
</tr>
<tr>
<td>Max hand load limit (static limit)</td>
<td>90kg/198lb</td>
</tr>
<tr>
<td>Finger carry load (static limit)</td>
<td>32kg/71lb</td>
</tr>
<tr>
<td>Time from open position to full power grip</td>
<td>1.2 seconds</td>
</tr>
<tr>
<td>Device Weight</td>
<td>Weight with quick disconnect wrist 469g (small) and 479g (regular) Weight with Wrist Disarticulation unit 405g (small) and 418g (regular)</td>
</tr>
</tbody>
</table>

9.2 i-limb access information

Hazardous Area Classification

The i-limb access device is not intended for use outside the boundaries of the environments listed below. The customer or user of the i-limb access device should assure that it is not used in such environments.

<table>
<thead>
<tr>
<th>Condition</th>
<th>Level</th>
</tr>
</thead>
<tbody>
<tr>
<td>Maximum temperature</td>
<td>+70˚C</td>
</tr>
<tr>
<td>Minimum temperature</td>
<td>-40˚C</td>
</tr>
<tr>
<td>Hazardous Area Classification</td>
<td>Non Hazardous</td>
</tr>
</tbody>
</table>

9.3 Component Compatibility

9.3.1 EMC and Electrical Information

Please refer to www.touchbionics.com/downloads/document-library for Electro Magnetic Compatibility (EMC) and Electrical Information for i-limb products.

9.4 Warranty

<table>
<thead>
<tr>
<th>Icon</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>☐</td>
<td>Consult instructions for use</td>
</tr>
<tr>
<td>☐</td>
<td>Class II equipment – provides double isolation to protect against electric shock</td>
</tr>
<tr>
<td>IP40</td>
<td>Degree of protection – IP40</td>
</tr>
<tr>
<td></td>
<td>Protection against penetration by solid particles with diameters larger than 1 mm. No special protection against penetration by water</td>
</tr>
<tr>
<td>▼SN</td>
<td>Serial Number</td>
</tr>
<tr>
<td></td>
<td>For i-limb access devices:</td>
</tr>
<tr>
<td></td>
<td>The unique serial number for i-limb ultra access devices is a “A” with a 4 digit alpha / numeric number.</td>
</tr>
<tr>
<td>☐</td>
<td>WEEE Compliance</td>
</tr>
<tr>
<td>☐</td>
<td>Catalogue number</td>
</tr>
<tr>
<td>☐</td>
<td>Manufacturer</td>
</tr>
<tr>
<td>☐</td>
<td>European Conformity</td>
</tr>
</tbody>
</table>

**Customer Service/Contact Information:**

Touch Bionics, Unit 3 Ashwood Court, Oakbank Park Way, Livingston EH53 0TH, UK  
Tel: Customer Service: +44 (0) 1506 438 556  

Touch Bionics, 35 Hampden Road  
Mansfield MA 02048, USA  
Tel: +1 855 MY iLIMB (694 5462)  
www.touchbionics.com
North American Customers
(Canada, Mexico and US)
Touch Bionics
35 Hampden Road
Mansfield MA 02048
USA
Tel: +1 855 MY iLIMB (694 5462)

International Customers
Touch Bionics
Unit 3, Ashwood Court
Oakbank Park Way
Livingston EH53 0TH
Scotland
Tel: +44 1506 438 556
Email: info@touchbionics.com

For address details and further information please visit www.touchbionics.com

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